ECO2N: A TOUGH2 Fluid Property Module for Mixtures of Water, NaCl, and CO₂

Karsten Pruess

Earth Sciences Division, Lawrence Berkeley National Laboratory
University of California, Berkeley, CA 94720

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Abstract

ECO2N is a fluid property module for the TOUGH2 simulator (Version 2.0) that was designed for applications to geologic sequestration of CO₂ in saline aquifers. It includes a comprehensive description of the thermodynamics and thermophysical properties of H₂O - NaCl - CO₂ mixtures, that reproduces fluid properties largely within experimental error for the temperature, pressure and salinity conditions of interest (10 °C ≤ T ≤ 110 °C; P ≤ 600 bar; salinity up to full halite saturation). Flow processes can be modeled isothermally or non-isothermally, and phase conditions represented may include a single (aqueous or CO₂-rich) phase, as well as two-phase mixtures. Fluid phases may appear or disappear in the course of a simulation, and solid salt may precipitate or dissolve. This report gives technical specifications of ECO2N and includes instructions for preparing input data. Code applications are illustrated by means of several sample problems, including problems that had been previously investigated in a code intercomparison study.
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1. Introduction

Injection of CO$_2$ into saline formations has been proposed as a means whereby emissions of heat-trapping greenhouse gases into the atmosphere may be reduced. Such injection would induce coupled processes of multiphase fluid flow, heat transfer, chemical reactions, and mechanical deformation. Several groups have developed simulation models for subsets of these processes. The present report describes a fluid property module "ECO2N" for the general-purpose reservoir simulator TOUGH2 (Pruess et al., 1999; Pruess, 2004), that can be used to model non-isothermal multiphase flow in the system H$_2$O - NaCl - CO$_2$. TOUGH2/ECO2N represents fluids as consisting of two phases: a water-rich aqueous phase, herein often referred to as "liquid," and a CO$_2$-rich phase referred to as "gas." In addition, solid salt may also be present. The only chemical reactions modeled by ECO2N include equilibrium phase partitioning of water and carbon dioxide between the liquid and gaseous phases, and precipitation and dissolution of solid salt. The partitioning of H$_2$O and CO$_2$ between liquid and gas phases is modeled as a function of temperature, pressure, and salinity, using the recently developed correlations of Spycher and Pruess (2005). Dissolution and precipitation of salt is treated by means of local equilibrium solubility. Associated changes in fluid porosity and permeability may also be modeled. All phases - gas, liquid, solid - may appear or disappear in any grid block during the course of a simulation. Thermodynamic conditions covered include a temperature range from ambient to 100 °C (approximately), pressures up to 600 bar, and salinity from zero to fully saturated. These parameter ranges should be adequate for most conditions encountered during disposal of CO$_2$ into deep saline aquifers.

ECO2N is written in Fortran 77 and is "plug-compatible" with TOUGH2, Version 2.0. The code is intrinsically single-precision, but requires 64-bit arithmetic, which on 32-bit processors (PCs and workstations) may be realized by using compiler options for generating 64-bit arithmetic. For example, on an IBM RS/6000 computer, this may be accomplished with the compiler option ":-qautodbl=dblpad". ECO2N may be linked with standard TOUGH2 modules like any of the fluid property modules included in the TOUGH2 V 2.0 package. As an example, we list the linking instruction that would be used on an IBM RS/6000 workstation.

```
f77 -o zco2n t2cg22.o meshm.o eco2n.o t2f.o t2solv.o ma28.o
```

Execution of an input file *rcc3* would be made with the command

```
zco2n <rcc3 >rcc3.out
```

- / -
The present report is a user's guide for the TOUGH2/ECO2N simulator. Information provided in the TOUGH2 users' guide (Pruess et al., 1999) is not duplicated here. We begin with a discussion of phase conditions and thermodynamic variables in the system H$_2$O - NaCl - CO$_2$, for conditions of interest in geologic sequestration of CO$_2$. This is followed by a discussion of our thermophysical property model, and guidance for preparing input data. Several sample problems are provided which document code performance and serve as a tutorial for applications.
2. Fluid Phases and Thermodynamic Variables in the System Water-NaCl-CO₂

In the two-component system water-CO₂, at temperatures above the freezing point of water and not considering hydrate phases, three different fluid phases may be present: an aqueous phase that is mostly water but may contain some dissolved CO₂, a liquid CO₂-rich phase that may contain some water, and a gaseous CO₂-rich phase that also may contain some water. Altogether there may be seven different phase combinations (Fig. 1). If NaCl ("salt") is added as a third fluid component, the number of possible phase combinations doubles, as in each of the seven phase combinations depicted in Fig. 1 there may or may not be an additional phase consisting of solid salt. Liquid and gaseous CO₂ may coexist along the saturated vapor pressure curve of CO₂, which ends at the critical point (T_{crit}, P_{crit}) = (31.04 °C, 73.82 bar; Vargaftik, 1975), see Fig. 2. At supercritical temperatures or pressures there is just a single CO₂-rich phase.

![Figure 1. Possible phase combinations in the system water-CO₂. The phase designations are a - aqueous, l - liquid CO₂, g - gaseous CO₂. Separate liquid and gas phases exist only at subcritical conditions.](image)

The present version of ECO2N can only represent a limited subset of the phase conditions depicted in Fig. 1. Thermophysical properties are accurately calculated for gaseous as well as for liquid CO₂, but no distinction between gaseous and liquid CO₂ phases is made in the treatment of flow, and no phase change between liquid and gaseous CO₂ is treated. Accordingly, of the seven phase combinations shown in Fig. 1, ECO2N can represent the ones numbered 1 (single-phase aqueous with or without dissolved CO₂ and salt), 2 and 3 (a single CO₂-rich phase that may be either liquid or gaseous CO₂, and may include dissolved water), and 4 and 5 (two-phase conditions consisting of an aqueous and a single CO₂-rich phase, with no distinction being made as to whether the CO₂-rich phase is liquid or gas). ECO2N cannot represent conditions 6 (two-phase mixture of...
Pressure

Temperature

\( P_{\text{crit}} = 73.82 \text{ bar} \)

\( T_{\text{crit}} = 31.04 \, ^\circ\text{C} \)

Figure 2. Phase states of CO₂.

liquid and gaseous CO₂) and 7 (three-phase). All sub- and super-critical CO₂ is considered as a single non-wetting phase, that will henceforth be referred to as "gas." ECO2N may be applied to sub- as well as super-critical temperature and pressure conditions, but applications that involve sub-critical conditions are limited to systems in which there is no change of phase between liquid and gaseous CO₂, and in which no mixtures of liquid and gaseous CO₂ occur.

Numerical modeling of the flow of brine and CO₂ requires a coupling of the phase behavior of water-salt-CO₂ mixtures with multiphase flow simulation techniques. Among the various issues raised by such coupling is the choice of notation. There are long-established notational conventions in both fields, which may lead to conflicts and misunderstandings when they are combined. In an effort to avoid confusion, we will briefly discuss notational issues pertaining to partitioning of CO₂ between an aqueous and a gaseous phase.

Phase partitioning is usually described in terms of mole fractions of the two components, which are denoted by \( x \) and \( y \), respectively, where \( x_1 = x_{\text{H2O}} \) and \( x_2 = x_{\text{CO2}} \) specify mole fractions in the aqueous phase, while \( y_1 = y_{\text{H2O}} \) and \( y_2 = y_{\text{CO2}} \) give mole fractions in the gas phase (Prausnitz et al., 1986; Spycher et al., 2003). We follow this notation, except that we add the subscript "eq" to emphasize that these mole fractions pertain to equilibrium partitioning of water and CO₂ between co-existing aqueous and gas phases. Accordingly, we denote the various mole
fractions pertaining to equilibrium phase partitioning as $x_{1,\text{eq}}, x_{2,\text{eq}}, y_{1,\text{eq}},$ and $y_{2,\text{eq}}$, while the corresponding mass fractions are denoted using upper-case X and Y. Mass fractions corresponding to single-phase conditions, where water and CO$_2$ concentrations are not constrained by phase equilibrium relations, are denoted by $X_1$ (for water) and $X_2$ (for CO$_2$) in the aqueous phase, and by $Y_1$ and $Y_2$ in the gas phase.

In the numerical simulation of brine-CO$_2$ flows, we will be concerned with the fundamental thermodynamic variables that characterize the brine-CO$_2$ system, and their change with time in different subdomains (grid blocks) of the flow system. Four "primary variables" are required to define the state of water-NaCl-CO$_2$ mixtures, which according to conventional TOUGH2 usage are denoted by $X1$, $X2$, $X3$, and $X4$. A summary of the fluid components and phases modeled by ECO2N, and the choice of primary thermodynamic variables, appears in Table 1. Different variables are used for different phase conditions, but two of the four primary variables are the same, regardless of the number and nature of phases present. This includes the first primary variable $X1$, denoting pressure, and the fourth primary variable $X4$ which is temperature. The second primary variable pertains to salt and is denoted $X_{\text{sm}}$ rather than $X2$ to avoid confusion with $X2$, the CO$_2$ mass fraction in the liquid phase. Depending upon whether or not a precipitated salt phase is present, the variable $X_{\text{sm}}$ has different meaning. When no solid salt is present, $X_{\text{sm}}$ denotes $X_s$, the salt mass fraction referred to the two-component system water-salt. When solid salt is present, $X_{\text{sm}}$ denotes $S_s$, the fraction of void space occupied by solid salt. The physical range of both $X_s$ and $S_s$ is $0, 1$; the reason for defining $X_{\text{sm}}$ by adding a number 10 to $S_s$ is to enable the presence or absence of solid salt to be recognized simply from the numerical value of the second primary variable. As had been mentioned above, the salt concentration variable $X_s$ is defined with respect to the two-component system H$_2$O - NaCl. This choice makes the salt concentration variable independent of CO$_2$ concentration, which simplifies the calculation of the partitioning of the H$_2$O and CO$_2$ components between the aqueous and gas phases (see below). In the three-component system H$_2$O - NaCl - CO$_2$, the total salt mass fraction in the aqueous phase will for given $X_s$ of course depend on CO$_2$ concentration. Salt mass fraction in the two-component system H$_2$O - NaCl can be expressed in terms of salt molality (moles m of salt per kg of water) as follows.
Table 1. Summary of ECO2N

<table>
<thead>
<tr>
<th>Components</th>
<th># 1: water</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td># 2: NaCl</td>
</tr>
<tr>
<td></td>
<td># 3: CO₂</td>
</tr>
</tbody>
</table>

Parameter choices

(NK, NEQ, NPH, NB) =

- (3, 4, 3, 6) water, NaCl, CO₂, nonisothermal (default)
- (3, 3, 3, 6) water, NaCl, CO₂, isothermal

Molecular diffusion can be modeled by setting NB = 8

Primary Variables

Single fluid phase (only aqueous, or only gas)# (P, X_{sm}, X_{3}, T)

- P - pressure
- X_{sm} - salt mass fraction $X_s$ in two-component water-salt system, or solid saturation $S_{s+10}$
- X_{3} - CO₂ mass fraction in the aqueous phase, or in the gas phase, in the three-component system water-salt-CO₂
- T - temperature

Two fluid phases (aqueous and gas)# (P, X_{sm}, S_{g+10}, T)

- P - pressure
- X_{sm} - salt mass fraction $X_s$ in two-component water-salt system, or solid saturation $S_{s+10}$
- S_{g} - gas phase saturation
- T - temperature

# When discussing fluid phase conditions, we refer to the potentially mobile (aqueous and gas) phases only; in all cases solid salt may precipitate or dissolve, adding another active phase to the system.

\[
X_s = \frac{mM_{NaCl}}{1000 + mM_{NaCl}} \tag{1}
\]

Here $M_{NaCl} = 58.448$ is the molecular weight of NaCl, and the number 1000 appears in the denominator because molality is defined as moles per 1000 g of water. For convenience we also list the inverse of Eq. (1).

\[
m = \frac{1000X_s/M_{NaCl}}{1 - X_s} \tag{2}
\]
The third primary variable $X_3$ is CO2 mass fraction ($X_2$) for single-phase conditions (only aqueous, or only gas) and is "gas saturation plus ten" ($S_g + 10$) for two-phase (aqueous and gas) conditions. The reason for adding 10 to $S_g$ is analogous to the conventions adopted for the second primary variable, namely, to be able to distinguish single-phase conditions ($0 \leq X_3 \leq 1$) from two-phase conditions ($10 \leq X_3 \leq 11$). In single-phase conditions, the CO2 concentration variable $X_2$ is "free," i.e., it can vary continuously within certain parameter ranges, while in two-phase aqueous-gas conditions, $X_2$ has a fixed value $X_{2,eq}$ that is a function of temperature, pressure, and salinity (see below). Accordingly, for single-phase conditions $X_2$ is included among the independent primary variables ($= X_3$), while for two-phase conditions, $X_2$ becomes a "secondary" parameter that is dependent upon primary variables ($T, P, X_s$). "Switching" primary variables according to phase conditions present provides a very robust and stable technique for dealing with changing phase compositions; see Section 2.2, below.

Initialization of a simulation with TOUGH2/ECO2N would normally be made with the internally used primary variables as listed in Table 1. For convenience of the user, additional choices are available for initializing a flow problem; see Section 4, below.

2.1 Phase Composition

The partitioning of H2O and CO2 among co-existing aqueous and gas phases is calculated from a slightly modified version of the correlations developed in (Spycher and Pruess, 2005). These correlations were derived from the requirement that chemical potentials of all components must be equal in different phases. For two-phase conditions, they predict the equilibrium composition of liquid (aqueous) and gas (CO2-rich) phases as functions of temperature, pressure, and salinity, and are valid in the temperature range $12 ^\circ C \leq T \leq 110 ^\circ C$, for pressures up to 600 bar, and salinity up to saturated NaCl brines. In the indicated parameter range, mutual solubilities of H2O and CO2 are calculated with an accuracy typically within experimental uncertainties. The modification made in ECO2N is that CO2 molar volumes are calculated using a tabular EOS based on Altunin's correlation (1975), instead of the Redlich-Kwong equation of state used in (Spycher and Pruess, 2005). This was done to maintain consistency with the temperature and pressure conditions for phase change between liquid and gaseous conditions used elsewhere in ECO2N. Altunin's correlations yield slightly different molar volumes than the Redlich-Kwong EOS whose parameters were fitted by Spycher and Pruess (2005) to obtain the best overall match between observed and predicted CO2 concentrations in the aqueous phase. The (small) differences in Altunin's molar volumes cause predictions for the mutual solubility of water and CO2 to be somewhat different also. However, the differences are generally small, see Figs. 3-5.
Figure 3. Dissolved CO₂ mass fractions in two-phase system at $T = 30 \, ^\circ\text{C}$ for pure water (0m) and 4-molal NaCl brine. Lines represent the original correlation of Spycher and Pruess (2005) that uses a Redlich-Kwong EOS for molar volume of CO₂. Symbols represent data calculated by ECO2N in which the molar volume of CO₂ is obtained from the correlations of Altunin (1975).

Figure 4. H₂O mass fractions in gas in two-phase system at $T = 30 \, ^\circ\text{C}$ for pure water (0m) and 4-molal NaCl brine. Lines represent the original correlation of Spycher and Pruess (2005) that uses a Redlich-Kwong EOS for molar volume of CO₂. Symbols represent data calculated by ECO2N in which the molar volume of CO₂ is obtained from the correlations of Altunin (1975).
Figure 5. Concentration of water in gas and CO$_2$ in the liquid (aqueous) phase at ($T, P$) = (45 °C, 216.18 bar), for salinities ranging from zero to fully saturated. Lines were calculated from the correlation of Spycher and Pruess (2005) that uses a Redlich-Kwong EOS for molar volume of CO$_2$. Symbols represent data calculated by ECO2N from a modified correlation in which the molar volume of CO$_2$ is obtained from the correlations of Altunin (1975).

For conditions of interest to geologic disposal of CO$_2$, equilibrium between aqueous and gas phases corresponds to a dissolved CO$_2$ mass fraction in the aqueous phase, $X_{2,eq}$, on the order of a few percent, while the mass fraction of water in the gas phase, $Y_{1,eq}$, is a fraction of a percent, so that gas phase CO$_2$ mass fraction $Y_{2,eq} = 1 - Y_{1,eq}$ is larger than 0.99. The relationship between CO$_2$ mass fraction $X_3$ and phase composition of the fluid mixture is as follows (see Fig. 6)

- $X_3 < X_{2,eq}$ corresponds to single-phase liquid conditions;
- $X_3 > Y_{2,eq}$ corresponds to single-phase gas;
- intermediate values ($X_{2,eq} \leq X_3 \leq Y_{2,eq}$) correspond to two-phase conditions with different proportions of aqueous and gas phases.

Dissolved NaCl concentrations may for typical sequestration conditions range as high as 6.25 molal. This corresponds to mass fractions of up to $X_{sm} = 26.7$ % in the two-component system water-salt. Phase conditions as a function of $X_{sm}$ are as follows.

- $X_{sm} \leq X_{EQ}$ corresponds to dissolved salt only;
- $X_{sm} > X_{EQ}$ corresponds to conditions of a saturated NaCl brine and solid salt.
Here XEQ denotes the equilibrium solubility of NaCl, which in ECO2N is evaluated as in EWASG (Battistelli et al., 1997) as a function of temperature, using an equation by Potter cited in Chou (1987). No dependence of XEQ on CO2 concentration is taken into account.

![Figure 6](image)

Figure 6. CO2 phase partitioning in the system H2O - NaCl - CO2. The CO2 mass fraction in brine-CO2 mixtures can vary in the range from 0 (no CO2) to 1 (no brine). X2,eq and Y2,eq denote, respectively, the CO2 mass fractions in aqueous and gas phases corresponding to equilibrium phase partitioning in two-phase conditions. Mass fractions less than X2,eq correspond to conditions in which only an aqueous phase is present, while mass fractions larger than Y2,eq correspond to single-phase gas conditions. Mass fractions intermediate between X2,eq and Y2,eq correspond to two-phase conditions with different proportions of aqueous and gas phases.

### 2.2 Phase Change

In single-phase (aqueous or gas) conditions, the third primary variable X3 is the CO2 mass fraction in that phase. In single-phase aqueous conditions, we must have X3 ≤ X2,eq, while in single-phase gas conditions, we must have X3 ≥ Y2,eq. The possibility of phase change is evaluated during a simulation by monitoring X3 in each grid block. The criteria for phase change from single-phase to two-phase conditions may be written as follows.

- **single-phase aqueous conditions**: a transition to two-phase conditions (evolution of a gas phase) will occur when X3 > X2,eq;
- **single-phase gas conditions**: a transition to two-phase conditions (evolution of an aqueous phase) will occur when X3 < Y2,eq = 1 - Y1,eq.

When two-phase conditions evolve in a previously single-phase grid block, the third primary variable is switched to X3 = S_g + 10. If the transition occurred from single-phase liquid conditions, the starting value of S_g is chosen as 10^-6; if the transition occurred from single-phase gas, the starting value is chosen as 1 - 10^-6.

In two-phase conditions, the third primary variable is X3 = S_g + 10. For two-phase conditions to persist, X3 must remain in the range (10, 11 - S_g). Transitions to single-phase conditions are recognized as follows.
• if $X_3 < 10$ (i.e., $S_g < 0$): gas phase disappears; make a transition to single-phase liquid conditions;
• if $X_3 > 11 - S_s$ (i.e., $S_g > 1 - S_s$): liquid phase disappears; make a transition to single-phase gas conditions.

Phase change involving (dis-)appearance of solid salt is recognized as follows. When no solid salt is present, the second primary variable $X_{sm}$ is the concentration (mass fraction referred to total water plus salt) of dissolved salt in the aqueous phase. The possibility of precipitation starting is evaluated by comparing $X_{sm}$ with $X_{EQ}$, the equilibrium solubility of NaCl at prevailing temperature. If $X_{sm} \leq X_{EQ}$ no precipitation occurs, whereas for $X_{sm} > X_{EQ}$ precipitation starts. In the latter case, variable $X_{sm}$ is switched to $S_s+10$, where solid saturation $S_s$ is initialized with a small non-zero value ($10^{-6}$). If a solid phase is present, the variable $X_{sm} = S_s+10$ is monitored. Solid phase disappears if $X_{sm} < 10$, in which case primary variable $X_{sm}$ is switched to salt concentration, and is initialized as slightly below saturation, $X_{sm} = X_{EQ} - 10^{-6}$.

2.3 Conversion of Units

The Spycher and Pruess (2005) model for phase partitioning in the system H$_2$O–NaCl–CO$_2$ is formulated in molar quantities (mole fractions and molalities), while TOUGH2/ECO2N describes phase compositions in terms of mass fractions. This section presents the equations and parameters needed for conversion between the two sets of units. The conversion between various concentration variables (mole fractions, molalities, mass fractions) does not depend upon whether or not concentrations correspond to equilibrium between liquid and gas phases; accordingly, the relations given below are valid regardless of the magnitude of concentrations.

Let us consider an aqueous phase with dissolved NaCl and CO$_2$. For a solution that is $m$-molal in NaCl and $n$-molal in CO$_2$, total mass per kg of water is

$$M = 1000 \text{ (g H}_2\text{O)} + m \text{ M}_{\text{NaCl}} \text{ (g NaCl)} + n \text{ M}_{\text{CO}_2} \text{ (g CO}_2)$$

where $\text{M}_{\text{NaCl}}$ and $\text{M}_{\text{CO}_2}$ are the molecular weights of NaCl and CO$_2$, respectively (see Table 2). Assuming NaCl to be completely dissociated, the total moles per kg of water are

$$m_T = \frac{1000}{\text{M}_{\text{H}_2\text{O}}} + 2m + n$$

The Spycher and Pruess (2005) correlations provide CO$_2$ mole fraction $x_2$ in the aqueous phase and H$_2$O mole fraction $y_1$ in the gas phase as functions of temperature, pressure, and salt
concentration (molality). For a CO₂ mole fraction \( x_2 \) we have \( n = x_2 m_T \) from which, using Eq. (4), we obtain

\[
n = \frac{x_2 (2m + 1000/M_{H2O})}{1 - x_2}
\]  

(5)

CO₂ mass fraction \( X_2 \) in the aqueous phase is obtained by dividing the CO₂ mass in \( n \) moles by the total mass,

\[
X_2 = \frac{n M_{CO2}}{1000 + m M_{NaCl} + n M_{CO2}}
\]

(6)

Water mass fraction \( Y_1 \) in the CO₂-rich phase is simply

\[
Y_1 = \frac{y_1 \cdot M_{H2O}}{y_1 \cdot M_{H2O} + (1 - y_1) M_{CO2}}
\]

(7)

The molecular weights of the various species are listed in Table 2 (Evans, 1982).

<table>
<thead>
<tr>
<th>species</th>
<th>mol. weight</th>
</tr>
</thead>
<tbody>
<tr>
<td>H₂O</td>
<td>18.016</td>
</tr>
<tr>
<td>Na</td>
<td>22.991</td>
</tr>
<tr>
<td>Cl</td>
<td>35.457</td>
</tr>
<tr>
<td>NaCl</td>
<td>58.448</td>
</tr>
<tr>
<td>CO₂</td>
<td>44.0</td>
</tr>
</tbody>
</table>

Table 2. Molecular weights in the system H₂O–NaCl–CO₂.
3. Thermophysical Properties of Water-NaCl-CO₂ Mixtures

Thermophysical properties needed to model the flow of water-salt-CO₂ mixtures in porous media include density, viscosity, and specific enthalpy of the fluid phases as functions of temperature, pressure, and composition, and partitioning of components among the fluid phases. Many of the needed parameters are obtained from the same correlations as were used in the EWASG property module of TOUGH2 (Battistelli et al., 1997). EWASG was developed for geothermal applications, and consequently considered conditions of elevated temperatures > 100 °C, and modest CO₂ partial pressures of order 1-10 bar. The present ECO2N module targets the opposite end of the temperature and pressure range, namely, modest temperatures below 110 °C, and high CO₂ pressures up to several hundred bar.

Water properties in TOUGH2/ECO2N are calculated, as in other members of the TOUGH family of codes, from the steam table equations as given by the International Formulation Committee (1967). Properties of pure CO₂ are obtained from correlations developed by Altunin et al. (1975). We began using Altunin's correlations in 1999 when a computer program implementing them was conveniently made available to us by Victor Malkovsky of the Institute of Geology of Ore Deposits, Petrography, Mineralogy and Geochemistry (IGEM) of the Russian Academy of Sciences, Moscow. Altunin's correlations were subsequently extensively cross-checked against experimental data and alternative PVT formulations, such as Span and Wagner (1996). They were found to be very accurate (García, 2003), so there is no need to change to a different formulation.

Altunin's correlations are not used directly in the code, but are used ahead of a TOUGH2/ECO2N simulation to tabulate density, viscosity, and specific enthalpy of pure CO₂ on a regular grid of (T, P)-values. These tabular data are provided to the ECO2N module in a file called "CO2TAB," and property values are obtained during the simulation by means of bivariate interpolation. Fig. 7 shows the manner in which CO₂ properties are tabulated, intentionally showing a coarse (T, P)-grid so that pertinent features of the tabulation may be better seen. (For actual calculations, we use finer grid spacings; the CO2TAB data file distributed with ECO2N covers the range 3.04 °C ≤ T ≤ 103.04 °C with ΔT = 2 °C and 1 bar ≤ P ≤ 600 bar with ΔP ≤ 4 bar in most cases. The ECO2N distribution includes a utility program for generating CO2TAB files if users desire a different T,P-range or different increments.) As shown in Fig. 7, the tabulation is made in such a way that for sub-critical conditions the saturation line is given by diagonals of the interpolation quadrangles. On the saturation line, two sets of data are provided, for liquid and gaseous CO₂, respectively, and in quadrangles that include points on both sides of the saturation line, points on the "wrong" side are excluded from the interpolation. This scheme provides for an efficient and accurate determination of thermophysical properties of CO₂.
Figure 7. Schematic of the temperature-pressure tabulation of CO₂ properties. The saturation line (dashed) is given by the diagonals of interpolation rectangles.

An earlier version of ECO2N explicitly associated partial pressures of water (vapor) and CO₂ with the gas phase, and calculated CO₂ dissolution in the aqueous phase from the CO₂ partial pressure, using an extended version of Henry's law (Pruess and García, 2002). The present version uses a methodology for calculating mutual solubilities of water and CO₂ (Spycher and Pruess, 2005) that is much more accurate, but has a drawback insofar as no partial pressures are associated with the individual fluid components. This makes it less straightforward to calculate thermophysical properties of the gas phase in terms of individual fluid components. We are primarily interested in the behavior of water-salt-CO₂ mixtures at moderate temperatures, T < 100 °C, say, where water vapor pressure is a negligibly small fraction of total pressure. Under these conditions the amount of water present in the CO₂-rich phase, henceforth referred to as "gas," is small. Accordingly, we approximate density, viscosity, and specific enthalpy of the gas phase by the corresponding properties of pure CO₂, without water present.

3.1 Density

Brine density ρ_b for the binary system water-salt is calculated as in Battistelli et al. (1997) from the correlations of Haas (1976) and Andersen et al. (1992). The calculation starts from aqueous phase density without salinity at vapor-saturated conditions, which is obtained from the correlations given by the International Formulation Committee (1967). Corrections are then applied
to account for effects of salinity and pressure. The density of aqueous phase with dissolved CO₂ is calculated assuming additivity of the volumes of brine and dissolved CO₂.

\[
\frac{1}{\rho_{aq}} = \frac{1-X_2}{\rho_b} + \frac{X_2}{\rho_{CO2}}
\]

(8)

where \(X_2\) is the mass fraction of CO₂ in the aqueous phase. Partial density of dissolved CO₂, \(\rho_{CO2}\), is calculated as a function of temperature from the correlation for molar volume of dissolved CO₂ at infinite dilution developed by García (2001).

\[
V_\phi = a + bT + cT^2 + dT^3
\]

(9)

In Eq. (9), molar volume of CO₂ is in units of cm³ per gram-mole, temperature \(T\) is in °C, and \(a–d\) are fit parameters given in Table 3.

| \(a\) | \(37.51\) |
| \(b\) | \(-9.585e-2\) |
| \(c\) | \(8.740e-4\) |
| \(d\) | \(-5.044e-7\) |

Table 3. Parameters for molar volume of dissolved CO₂ (Eq. 9)

Partial density of dissolved CO₂ in units of kg/m³ is then

\[
\rho_{CO2} = \frac{M_{CO2}}{V_\phi} \times 10^3
\]

(10)

where \(M_{CO2} = 44.0\) is the molecular weight of CO₂.

Dissolved CO₂ amounts at most to a few percent of total aqueous density. Accordingly, dissolved CO₂ is always dilute, regardless of total fluid pressure. It is then permissible to neglect the pressure dependence of partial density of dissolved CO₂, and to use the density corresponding to infinite dilution.
As had been mentioned above, the density of the CO\textsubscript{2}-rich (gas) phase is obtained by neglecting effects of water, and approximating the density by that of pure CO\textsubscript{2} at the same temperature and pressure conditions. Density is obtained through bivariate interpolation from a tabulation of CO\textsubscript{2} densities as function of temperature and pressure, that is based on the correlations developed by Altunin (1975).

### 3.2 Viscosity

Brine viscosity is obtained as in EWASG from a correlation presented by Phillips et al. (1981), that reproduces experimental data in the temperature range from 10–350 °C for salinities up to 5 molal and pressures up to 500 bar within 2 %. No allowance is made for dependence of brine viscosity on the concentration of dissolved CO\textsubscript{2}. Viscosity of the CO\textsubscript{2}-rich phase is approximated as being equal to pure CO\textsubscript{2}, and is obtained through tabular interpolation from the correlations of Altunin (1975).

### 3.3 Specific Enthalpy

Specific enthalpy of brine is calculated from the correlations developed by Lorenz et al. (2000), which are valid for all salt concentrations in the temperature range from 25 °C ≤ T ≤ 300 °C. The enthalpy of aqueous phase with dissolved CO\textsubscript{2} is obtained by adding the enthalpies of the CO\textsubscript{2} and brine (pseudo-) components, and accounting for the enthalpy of dissolution of CO\textsubscript{2}.

\[
\begin{align*}
\text{h}_{\text{aq}} & = (1 - X_2) \text{h}_b + X_2 \text{h}_{\text{CO}_2,aq} \\
\end{align*}
\]

\[\text{h}_{\text{CO}_2,aq} = \text{h}_{\text{CO}_2} + \text{h}_{\text{dis}}\]

\[\text{h}_{\text{CO}_2,aq}(T,P,X_s) = \text{h}_{\text{CO}_2,g}(T,P) + \text{h}_{\text{dis},g}(T,X_s)\]

where \(\text{h}_{\text{dis},g}\) is obtained as in Battistelli et al. (1997) from an equation due to Himmelblau (1959). For geologic sequestration we are primarily interested in liquid-like (high-pressure) CO\textsubscript{2}, for which the specific enthalpy of dissolved CO\textsubscript{2} may be written

\[
\begin{align*}
\text{h}_{\text{CO}_2,aq}(T,P,X_s) & = \text{h}_{\text{CO}_2,l}(T,P) + \text{h}_{\text{dis},l}(T,X_s) \\
\end{align*}
\]
Here $h_{\text{dis},l}$ is the specific heat of dissolution for liquid-like CO$_2$. Along the CO$_2$ saturation line, liquid and gaseous CO$_2$ phases may co-exist, and the expressions Eqs. (12, 13) must be equal there. We obtain

$$h_{\text{dis},l}(T, X_s) = h_{\text{dis},g}(T, X_s) + h_{\text{CO}_2,gl}(T)$$

(14)

where $h_{\text{CO}_2,gl}(T) = h_{\text{CO}_2,g}(T, P_s) - h_{\text{CO}_2,l}(T, P_s)$ is the specific enthalpy of vaporization of CO$_2$, and $P_s = P_s(T)$ is the saturated vapor pressure of CO$_2$ at temperature $T$. Depending upon whether CO$_2$ is in gas or liquid conditions, we use Eq.(12) or (13) in Eq. (11) to calculate the specific enthalpy of dissolved CO$_2$. At the temperatures of interest here, $h_{\text{dis},g}$ is a negative quantity, so that dissolution of low-pressure CO$_2$ is accompanied by an increase in temperature. $h_{\text{CO}_2,gl}$ is a positive quantity, which will reduce or cancel out the heat-of-dissolution effects. This indicates that dissolution of liquid CO$_2$ will produce less temperature increase than dissolution of gaseous CO$_2$, and may even cause a temperature decline if $h_{\text{CO}_2,gl}$ is sufficiently large.

Application of Eq. (11) is straightforward for single-phase gas and two-phase conditions, where $h_{\text{CO}_2}$ is obtained as a function of temperature and pressure through bivariate interpolation from a tabulation of Altunin's correlation (1975). A complication arises in evaluating $h_{\text{CO}_2}$ for single-phase aqueous conditions. We make the assumption that $h_{\text{CO}_2}(P, X_s, X_2, T)$ for single-phase liquid is identical to the value in a two-phase system with the same composition of the aqueous phase. To determine $h_{\text{CO}_2}$, it is then necessary to invert the Spycher and Pruess (2005) phase partitioning relation $X_2 = X_2(P; T, X_s)$, in order to obtain the pressure $P$ in a two-phase aqueous-gas system that would correspond to a dissolved CO$_2$ mass fraction $X_2$ in the aqueous phase, $P = P(X_2; X_s, T)$. The inversion is accomplished by Newtonian iteration, using a starting guess $P_0$ for $P$ that is obtained from Henry's law. Specific enthalpy of gaseous CO$_2$ in the two-phase system is then calculated as $h_{\text{CO}_2} = h_{\text{CO}_2}(T, P)$, and specific enthalpy of dissolved CO$_2$ is $h_{\text{CO}_2} + h_{\text{dis}}$. 

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4. Preparation of Input Data

Most of TOUGH2/ECO2N input specifications correspond to the general TOUGH2 input formats as given in the TOUGH2 user's guide (Pruess et al., 1999). This information is not duplicated in the present report; here we discuss only parameter choices specific to ECO2N.

4.1 Initialization Choices

Flow problems in TOUGH2/ECO2N will generally be initialized with the primary thermodynamic variables as used in the code, but some additional choices are available for the convenience of users. The internally used variables are \((P, X_{sm}, X, T)\) for grid blocks in single-phase (liquid or gas) conditions and \((P, X_{sm}, S_g+10, T)\) for two-phase (liquid and gas) grid blocks (see Table 1). Here \(X\) is the mass fraction of CO\(_2\) in the fluid. As had been discussed above, for conditions of interest to geologic sequestration of CO\(_2\), \(X\) is restricted to small values \(0 \leq X \leq X_{2,eq}\) (a few percent) for single-phase liquid conditions, or to values near 1 \((Y_{2,eq} \leq X \leq 1, \text{ with } Y_{2,eq} > 0.99 \text{ typically})\) for single-phase gas (Fig. 6). Intermediate values \(X_{2,eq} < X < Y_{2,eq}\) correspond to two-phase conditions, and thus should be initialized by specifying \(S_g+10\) as third primary variable. As a convenience to users, ECO2N allows initial conditions to be specified in the full range \(0 \leq X \leq 1\). During the initialization phase of a simulation, a check is made whether \(X\) is in fact within the range of mass fractions that correspond to single-phase (liquid or gas) conditions. If this is found not to be the case, the conditions are recognized as being two-phase, and the corresponding gas saturation is calculated from the phase equilibrium constraint.

\[
X_3 \left( S_l \rho_l + S_g \rho_g \right) = S_l \rho_l X_{2,eq} + S_g \rho_g Y_{2,eq}
\]  

(15)

Using \(S_l = 1 - S_g - S_s\), with \(S_s\) the "solid saturation" (fraction of pore space occupied by solid salt), we obtain

\[
S_g = A \times (1 - S_s)
\]

(16)

and the third primary variable is reset internally to \(X = S_g + 10\). Here the parameter \(A\) is given by

\[
A = \frac{\left( X_3 - X_{2,eq} \right) \rho_l}{\left( X_3 - X_{2,eq} \right) \rho_l + \left( Y_{2,eq} - X_3 \right) \rho_g}
\]

(17)

Users may think of specifying single-phase liquid (aqueous) conditions by setting \(X = 10\) (corresponding to \(S_g = 0\)), and single-phase gas conditions by setting \(X = 11 - S_s\) (corresponding
to \( S_l = 0 \). Strictly speaking this is not permissible, because two-phase initialization requires that both \( S_g > 0 \) and \( S_l > 0 \). Single-phase states should instead be initialized by specifying primary variable \( X_3 \) as CO2 mass fraction. However, as a user convenience, ECO2N accepts initialization of single-phase liquid conditions by specifying \( X_3 = 10 \) (\( S_g = 0 \)). Such specification will be converted internally to two-phase in the initialization phase by adding a small number \((10^{-11})\) to the third primary variable, changing conditions to two-phase with a small gas saturation \( S_g = 10^{-11} \).

Salt concentration or saturation of solid salt, if present, is characterized in ECO2N by means of the second primary variable \( X_{sm} \). When no solid phase is present, \( X_{sm} \) denotes \( X_s \), the mass fraction of NaCl referred to the two-component system water-NaCl. This is restricted to the range \( 0 \leq X_{sm} \leq X_{EQ} \), where \( X_{EQ} = X_{EQ}(T) \) is the solubility of salt. For \( X_{sm} > 10 \) this variable means \( S_s + 10 \), solid saturation plus 10. Users also have the option to specify salt concentration by means of molality \( m \) by assigning \( X_{sm} = -m \). Such specification will in the initialization phase be internally converted to \( X_s \) by using Eq. (1). When salt concentration (as a fraction of total \( H_2O + NaCl \) mass) exceeds \( X_{EQ} \), this corresponds to conditions in which solid salt will be present in addition to dissolved salt in the aqueous phase. Such states should be initialized with a second primary variable \( X_{sm} = S_s + 10 \). However, ECO2N accepts initialization with \( X_{sm} > X_{EQ} \), recognizes this as corresponding to presence of solid salt, and converts the second primary variable internally to the appropriate solid saturation that will result in total salt mass fraction in the binary system water-salt being equal to \( X_{sm} \). The conversion starts from the following equation.

\[
X_{sm} = \frac{X_{EQ} \times S_l \rho_l (1 - X_2) + S_s \rho_s}{S_l \rho_l (1 - X_2) + S_s \rho_s}
\]

(18)

where the numerator gives the total salt mass per unit volume, in liquid and solid phases, while the denominator gives the total mass of salt plus water. Substituting \( S_l = 1 - S_g - S_s \), this can be solved for \( S_s \) to yield

\[
S_s = \frac{B \times (1 - S_g)}{1 + B}
\]

(19)

where the parameter \( B \) is given by

\[
B = \frac{(X_{sm} - X_{EQ}) \rho_l (1 - X_2)}{\rho_s (1 - X_{sm})}
\]

(20)
The most general conditions arise when both the second and third primary variables are initialized as mass fractions, nominally corresponding to single-phase fluid conditions with no solid phase present, but both mass fractions being in the range corresponding to two-phase fluid conditions with precipitated salt. Under these conditions, Eqs. (16) and (19) are solved simultaneously in ECO2N for $S_s$ and $S_g$, yielding

$$S_g = \frac{A}{1 + B - A \times B}$$

and

$$S_s = \frac{B \times (1 - A)}{1 + B - A \times B}$$

Then both second and third primary variables are converted to phase saturations, $S_s + 10$ and $S_g + 10$, respectively. Examples of different initialization choices are given in sample problem 1, below.

4.2 Permeability Change from Precipitation and Dissolution of Salt

ECO2N offers several choices for the functional dependence of relative change in permeability, $k/k_0$, on relative change in active flow porosity.

$$\frac{k}{k_0} = f\left(\frac{\phi_f}{\phi_0}\right) = f\left(1 - S_s\right)$$

The simplest model that can capture the converging-diverging nature of natural pore channels consists of alternating segments of capillary tubes with larger and smaller radii, respectively; see Fig. 8. While in straight capillary tube models permeability remains finite as long

(a) conceptual model

(b) tubes-in-series

Figure 8. Model for converging-diverging pore channels.
as porosity is non-zero, in models of tubes with different radii in series, permeability is reduced to zero at a finite porosity. From the tubes-in-series model shown in Fig. 8, the following relationship can be derived (Verma and Pruess, 1988)

\[
\frac{k}{k_0} = \theta^2 \frac{1 - \Gamma + \Gamma/\omega^2}{1 - \Gamma + \Gamma[\theta/(\theta + 1)]^2}
\]  

(24)

Here

\[
\theta = \frac{1 - S_s - \phi_r}{1 - \phi_r}
\]  

(25)

depends on the fraction 1-\(S_s\) of original pore space that remains available to fluids, and on a parameter \(\phi_r\), which denotes the fraction of original porosity at which permeability is reduced to zero. \(\Gamma\) is the fractional length of the pore bodies, and the parameter \(\omega\) is given by

\[
\omega = 1 + \frac{1/\Gamma}{1/\phi_r - 1}
\]  

(26)

Therefore, Eq. (24) has only two independent geometric parameters that need to be specified, \(\phi_r\) and \(\Gamma\). As an example, Fig. 9 shows the permeability reduction factor from Eq. (24), plotted against \(\phi/\phi_0 = (1 - S_s)\), for parameters of \(\phi_r = \Gamma = 0.8\).
For parallel-plate fracture segments of different aperture in series, a relationship similar to Eq. (24) is obtained, the only difference being that the exponent 2 is replaced everywhere by 3 (Verma and Pruess, 1988). If only straight capillary tubes of uniform radius are considered, we have $\phi_r = 0$, $\Gamma = 0$, and Eq. (24) simplifies to

$$\frac{k}{k_0} = (1-S_s)^2$$

(27)

### 4.3 Choice of Program Options

Various options for ECO2N can be selected through parameter specifications in data block SELEC. Default choices corresponding to various selection parameters set equal to zero provide the most comprehensive thermophysical property model. Certain functional dependencies can be turned off or replaced by simpler and less accurate models, see below. These options are offered to enable users to identify the role of different effects in a flow problem, and to facilitate comparison with other simulation programs that may not include full dependencies of thermophysical properties.

**SELECTION** keyword to introduce a data block with parameters for ECO2N.

**Record SELEC.1**

Record format (16I5)

IE(I), I=1,16

IE(1) set equal to 1, to read one additional data record (a larger value with more data records is acceptable, but only one additional record will be used by ECO2N).

IE(11) selects dependence of permeability on the fraction $\phi_f / \phi_0 = (1-S_s)$ of original pore space that remains available to fluids.

0: permeability does not vary with $\phi_f$.
1: $k/k_0 = (1-S_s)^\gamma$, with $\gamma = FE(1)$ (record SELEC.2).
2: fractures in series, i.e., Eq. (24) with exponent 2 everywhere replaced by 3.
3: tubes-in-series, i.e., Eq. (24).

IE(12) allows choice of model for water solubility in CO2

0: after Spycher and Pruess (2005).
1: evaporation model; i.e., water density in the CO2-rich phase is calculated as density of saturated water vapor at prevailing temperature and salinity.

IE(13) allows choice of dependence of brine density on dissolved CO2
0: brine density varies with dissolved CO₂ concentration, according to García's (2001) correlation for temperature dependence of molar volume of dissolved CO₂.
1: brine density is independent of CO₂ concentration.

IE(14) allows choice of treatment of thermophysical properties as a function of salinity
0: full dependence.
1: no salinity dependence of thermophysical properties (except for brine enthalpy; salt solubility constraints are maintained).

IE(15) allows choice of correlation for brine enthalpy at saturated vapor pressure
0: after Lorenz et al. (2000).

Record SELEC.2 introduces parameters for functional dependence of permeability on solid saturation

Format(8E10.4)
FE(1), FE(2)
FE(1) parameter γ (for IE(11)=1); parameter φr (for IE(11) = 2, 3)
FE(2) parameter Γ (for IE(11) = 2, 3)

The ECO2N module includes a customized version of a subroutine FGTAB that can write data files FOFT, COFT, and GOFT with time series of conditions at user-selected grid blocks and connections for plotting. The parameters written out in comma-delimited format at each time step are as follows.

FOFT: (gas) pressure, dissolved CO₂ mass fraction in liquid, gas saturation, dissolved salt mass fraction and solid saturation (fraction of void space taken up by solid precipitate);

COFT: flow rates of gas, liquid, and total CO₂ (as free phase and dissolved in aqueous phase);

GOFT: well flow rate, flowing enthalpy, flowing CO₂ mass fraction, gas mass fraction of well flow, flowing wellbore pressure (production wells only).
5. Sample Problems

This section presents a number of sample problems for TOUGH2/ECO2N. The problems were chosen to demonstrate the preparation of input data, to illustrate code capabilities, and to provide benchmarks for proper code installation. Three of the problems were taken from a recent code intercomparison study, in which ten groups from six countries exercised different simulation codes to generate results for a suite of test problems (Pruess et al., 2002, 2004). These problems include a basic injection problem (Section 5.2), a basic fault leakage problem (Section 5.3), and a CO$_2$ storage problem with 2-D geometry loosely patterned after the Sleipner Vest CO$_2$ injection project (Kongsjorden et al., 1997; Lindeberg et al., 2002) in the Norwegian sector of the North Sea (Section 5.4). In order to provide some context and perspective the current TOUGH2/ECO2N results are compared with results previously obtained in the CO$_2$ code intercomparison project.

5.1 Problem No. 1 (*rtab*) - Demonstration of Initialization Options

The input file as given in Fig. 10 performs just a single infinitesimal time step ($\Delta t = 10^{-9}$ s) and includes neither flow connections between grid blocks nor sinks or sources. Therefore, there is no flow and no changes in the initially specified thermodynamic conditions. The purpose of this problem is simply to demonstrate different options for initializing thermodynamic conditions.

*rtab* ... initialization test for ECO2N
ROCKS----1----*----2----*----3----*----4----*----5----*----6----*----7----*----8
SANDS   2  2600.e00       .35  100.e-15  100.e-15  100.e-15      2.51      920.
                             4.5e-10
                             7       .457   .30    1.       .05
                             7       .457   .00   5.1e-5   1.e7      .999
MULTI----1----*----2----*----3----*----4----*----5----*----6----*----7----*----8
             3       4       3       6
START----1----*----2----*----3----*----4----*----5----*----6----*----7----*----8
             1
PARAM----1----*----2----*----3----*----4----*----5----*----6----*----7----*----8
             1  1       110 0900000000  4    3
                      -1.
             1.e-9
             1.E-5  1.E00
             60.e5
SELEC....2....3....4....5....6....7....8....9....10....11....12....13....14....15....16
             1
             0       0       0       0       0       0       0       0
             0   8   8
ELEME----1----*----2----*----3----*----4----*----5----*----6----*----7----*----8
a  1    10    1SANDS    1.
A  14    7    1SANDS    1.
CONNE----1----*----2----*----3----*----4----*----5----*----6----*----7----*----8

Figure 10. TOUGH2/ECO2N input file (first part) for sample problem 1 - demonstration of initialization options.
Standard initialization with internally used primary variables (Table 1) is made for a number of grid blocks in single-phase liquid conditions (*a 1*, *a 3*, *a 5*), single-phase gas (*a 10*), and two-phase fluid (*A 14*, *A 15*, *A 19*). Several grid blocks are initialized with single-phase type primary variables, but with a CO₂ mass fraction (primary variable #3) that is larger than can be dissolved in the aqueous phase, and smaller than required for single-phase gas conditions (*a 2*, *a 6*, *a 9*, *A 18*). The CO₂ mass fractions for these blocks correspond to two-phase (liquid-gas) fluid conditions (see Fig. 6 and Section 4.1), and are
internally converted to the appropriate gas saturation in the initialization phase. Primary variable #3 is then re-set to $S_g + 10$, as can be seen from the list of internally used primary variables that is generated by this problem (Fig. 11). Grid block *A 16* is initialized with primary variable #3 corresponding to internal ECO2N usage, but primary variable #2 is larger than saturated salt mass fraction in the binary system water-salt. This specification corresponds to presence of solid salt, and is internally converted to $S_s + 10$. In some grid blocks both primary variables #2 and #3 are specified with conventions applicable for single-phase liquid conditions, but with salt mass fraction exceeding the solubility limit, and CO$_2$ mass fraction being in the intermediate range between the liquid and gas phase limits (*a 4*, *a 7*, *a 8*, *a 11*, *A 17*). Salt as well as CO$_2$ mass fractions for these blocks are converted to the appropriate internally used saturation variables. Finally, there are grid blocks (*A 20*, *A 21*) in which primary variable #2 is specified as salt molality (counted by convention as undissociated) in the binary water-salt system, which is internally converted to salt mass fraction. The internally used primary variables generated from the INCON data given in Fig. 10 are shown in Fig. 11. Fig. 12 shows part of the printed output for this problem.

We emphasize that the preferred and recommended option is to initialize flow problems by means of the internally used primary variables (Table 1). The options of allowing salt and CO$_2$ mass fractions that are out of range were created as a convenience to users, to avoid "erroneous initialization" errors when running TOUGH2/ECO2N.

**PRIMARY VARIABLES**

| AT ELEMENT *a 1* --- | $4.00000E+07$ | $0.00000E+00$ | $3.90000E-01$ | $3.00000E+02$ |
| AT ELEMENT *a 2* --- | $4.00000E+07$ | $0.00000E+00$ | $1.08654E+02$ | $3.00000E+02$ |
| AT ELEMENT *a 3* --- | $3.40000E+08$ | $0.00000E+00$ | $6.60000E-01$ | $3.00000E+02$ |
| AT ELEMENT *a 4* --- | $3.40000E+08$ | $1.00080E+02$ | $1.06980E+02$ | $3.00000E+02$ |
| AT ELEMENT *a 5* --- | $1.40000E+08$ | $1.04660E+00$ | $3.60000E-01$ | $3.00000E+02$ |
| AT ELEMENT *a 6* --- | $1.40000E+08$ | $1.04660E+00$ | $1.03947E+02$ | $3.00000E+02$ |
| AT ELEMENT *a 7* --- | $1.40000E+08$ | $1.01996E+02$ | $1.00239E+02$ | $3.00000E+02$ |
| AT ELEMENT *a 8* --- | $1.40000E+08$ | $1.01265E+02$ | $1.03812E+02$ | $3.00000E+02$ |
| AT ELEMENT *a 9* --- | $1.40000E+08$ | $1.05000E+02$ | $1.04969E+02$ | $3.00000E+02$ |
| AT ELEMENT *a 10* --- | $1.40000E+08$ | $1.05000E+02$ | $9.99000E+00$ | $3.00000E+02$ |
| AT ELEMENT *a 11* --- | $1.40000E+08$ | $1.00160E+02$ | $1.09923E+02$ | $3.00000E+02$ |
| AT ELEMENT *a 14* --- | $2.16180E+08$ | $5.00000E-01$ | $1.05000E+02$ | $4.50000E+02$ |
| AT ELEMENT *a 15* --- | $2.16180E+08$ | $1.05000E+02$ | $1.05000E+02$ | $4.50000E+02$ |
| AT ELEMENT *a 16* --- | $2.16180E+08$ | $1.01016E+02$ | $1.05000E+02$ | $4.50000E+02$ |
| AT ELEMENT *a 17* --- | $2.16180E+08$ | $1.00957E+02$ | $1.05287E+02$ | $4.50000E+02$ |
| AT ELEMENT *a 18* --- | $2.16180E+08$ | $1.02000E+02$ | $1.04677E+02$ | $4.50000E+02$ |
| AT ELEMENT *a 19* --- | $2.16180E+08$ | $1.02000E+02$ | $1.05000E+02$ | $4.50000E+02$ |
| AT ELEMENT *a 20* --- | $2.16180E+08$ | $1.04661E+00$ | $1.05000E+02$ | $4.50000E+02$ |
| AT ELEMENT *a 21* --- | $2.16180E+08$ | $2.59637E+00$ | $1.05000E+02$ | $4.50000E+02$ |

Figure 11. Primary variables internally used in ECO2N for the INCON data given in Fig. 10.
Figure 12. Output data for sample problem 1.
5.2 Problem No. 2 (*rcc3*) - Radial Flow from a CO₂ Injection Well

This is a basic problem of CO₂ injection into a saline aquifer, examining two-phase flow with CO₂ displacing (saline) water under conditions that may be encountered in brine aquifers at a depth of the order of 1.2 km. A CO₂ injection well fully penetrates a homogeneous, isotropic, infinite-acting aquifer of 100 m thickness (Fig. 13), at conditions of 120 bar pressure, 45 °C temperature, and a salinity of 15 % by weight. CO₂ is injected uniformly at a constant rate of 100 kg/s. This problem had been included as test problem #3 in a recent code intercomparison project (Pruess et al., 2002, 2004); full specifications are given in Appendix A.

![Figure 13. Schematic of sample problem 2.](image)

The TOUGH2 input file used for grid generation is shown in Fig. 14. The well is modeled as a circular grid element of R = 0.3 m (= 12"). The numerical grid is extended to a large distance of 100 km, so that the system would be infinite-acting for the time period simulated (10,000 days, 27.38 years). Prior to the flow simulation, a minor amount of editing is performed on the MESH file. The well block is assigned to a domain #2, with a view on facilitating running of a non-isothermal variation of the problem. Further, the nodal distance corresponding to the well block was changed to an infinitesimal value. A fragment of the modified MESH file is shown in Fig. 15, and the TOUGH2 input file used for the simulation is shown in Fig. 16. The simulation is performed in isothermal mode (NEQ = 3 in data block MULTI). A separate ROCKS domain 'well ' with "infinite" rock grain density was included in the input file to enable running of a non-isothermal
variation simply by setting NEQ = 4; the well block "A1 1" is assigned to domain 'well' with "infinite" rock grain density, so that CO₂ injection would effectively occur at initial temperature of 45 °C, obviating the need for specifying an injection enthalpy. Part of the output generated from this problem is shown in Fig. 17. As can be seen salt is precipitating around the injection well, but associated permeability reduction is turned off (IE(11) = 0).

An important advantage of the radial flow problem considered here is that it admits a similarity solution. Specifically, the solution depends on radial distance R and time t only through the similarity variable \( \xi = R^2/t \), even when taking into account all the non-linearities due to PVT
... Code Intercomparison problem3: Radial flow from a CO2 Injection Well

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Figure 16. TOUGH2 input file for radial injection problem.

properties and two-phase flow (O’Sullivan, 1981; Doughty and Pruess, 1992). The space and time
discretization employed for finite difference simulation will violate the rigorous $R^2/t$ invariance, so
that the similarity property will be maintained only approximately. The accuracy of the numerical
simulation can be checked by plotting the results as a function of the similarity variable $R^2/t$ (Figs.
18 - 23). Fig. 18 shows the results for pressure as a function of the similarity variable. Data were
plotted from the pressure profile obtained at a simulation time of $t = 8.64 \times 10^7$ s, and from the time
series data for grid block A1 49, at a radial distance of $R = 25.25$ m, that were generated by means
of FOFT specifications in the input file (Fig. 16). The agreement between the profile data (shown
as thick solid lines) and the time series data (shown as thick dashed lines) is excellent,
... ... AT [ 1, 1] -------- DELTEX = .100000E+01 MAX. RES. = .353732E+01 AT ELEMENT A1 1 EQUATION 3
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confirmed the approximate preservation of the similarity property in the numerical solution. Minor deviations in the time series data at values $R^2/t < 10^{-5}$ m$^2$/s correspond to conditions at very large times, where effects of the finite system size are beginning to be felt. Fig. 19 presents simulated results for gas saturation as a function of the similarity variable, showing three distinct regions emerging from the CO$_2$ injection process. The first region with $R^2/t \leq 1.3 \times 10^{-5}$ m$^2$/s corresponds to a zone where complete dry-out of aqueous phase has occurred. Gas saturation in this region is slightly less than 1, however, due to the presence of solid precipitate (Fig. 20). The dry-out zone is followed by an intermediate zone extending to $R^2/t \approx 1.3 \times 10^{-5}$ m$^2$/s where liquid and gas phases coexist. Finally, there is an outer region with $R^2/t > 10^{-2}$ m$^2$/s in which single-phase liquid conditions prevail.
For comparison Figs. 18 - 22 also include results generated by LBNL for the code intercomparison project with an earlier version of the ECO2N-module. The main difference to the present simulation is that the earlier version used an evaporation model for H₂O partitioning into the CO₂-rich phase. We ran a problem variation using the evaporation model with the present ECO2N module (IE(12)=1), and obtained results that were virtually identical to the previous LBNL results in the code intercomparison project. Fig. 23 shows that the evaporation model strongly underestimates the amount of water dissolving into the CO₂-rich phase. The Spycher and Pruess (2005) model for phase partitioning produces a more vigorous drying process, accelerating the growth of a dry-out zone around the injection well (Fig. 19), and giving rise to increased salt precipitation (Fig. 20). The larger extent of the dry-out zone and increased salt precipitation there are the only significant differences in comparison to the earlier LBNL results. The peculiar behavior of NaCl mass fraction in liquid seen in Fig. 22 is due to dissolution of CO₂. At large R²/t > 10⁻² m²/s, NaCl mass fraction is unchanged from the initial value of 0.15. The modest reduction of NaCl mass fraction to approximately 0.146 in the two-phase zone (1.3x10⁻⁵ m²/s < R²/t < 10⁻² m²/s) is due to the volume increase of the aqueous phase upon CO₂ dissolution. The sharp peak in NaCl concentration at the inner boundary of the two-phase zone (R²/t ≈ 1.3x10⁻⁵ m²/s) occurs because conditions are approaching dry-out there.
Figure 18. Simulated pressures as a function of the similarity variable. The thick solid line represents a spatial profile at a simulation time of $8.64 \times 10^7$ s, while the thick dashed line represents a time series of data for a grid block at a radial distance of $R = 25.25$ m. The thin line gives the results previously submitted by LBNL to the code intercomparison project, that were obtained with an earlier version of the ECO2N module.
Figure 19. Simulated gas saturations.

Figure 20. Simulated solid saturations.
Figure 21. Simulated CO₂ mass fraction in aqueous phase.

Figure 22. Simulated NaCl mass fraction in aqueous phase.
Figure 23. Simulated water mass fraction in CO$_2$-rich phase.
5.3 Problem No. 3 (*r1dv*) - CO₂ Discharge Along a Fault Zone

The amounts of CO₂ that would need to be disposed of at fossil-fueled power plants are very large. A coal-fired plant with a capacity of 1,000 MWe generates approximately 30,000 tonnes of CO₂ per day (Hitchon 1996). When disposed of into brine formations, CO₂ injection plumes would over time extend to large distances of the order of ten kilometers or more, making it likely that geologic discontinuities such as faults and fractures will be encountered, with an associated potential for CO₂ losses from the primary disposal aquifer. CO₂ leaks through caprock discontinuities have a potential for self-enhancement, because pressures can actually decrease and/or flow rates increase as escaping CO₂ creates a pathway towards shallower strata. It is not known whether or not it may be possible for a runaway process to develop where an initially "small" leak could accelerate and grow over time to the point of an eruptive release.

Migration of CO₂ along a water-saturated fault zone would be subject to gravitational and viscous instabilities, and would likely involve complex two- and three-dimensional flow effects. As a first approximation to this kind of problem, we consider here a highly simplified situation in which a potential CO₂ leakage path is modeled as a 1-D column (Fig. B.1). This problem was also included as #4 in the code intercomparison project (Pruess et al., 2002, 2004); specifications are given in Appendix B.

The problem is run in two segments. A first run segment obtains gravity equilibrium relative to a pressure of 100 bar prescribed at the top boundary. The gravity-equilibrated conditions are then used as initial conditions in a second run segment, where conditions of P = 240 bar and a mass fraction $X_{CO₂} = 1$ are maintained at the lower boundary, while upper boundary conditions are unchanged. Note that the CO₂ discharge conditions correspond to a large overpressure, exceeding initial hydrostatic pressure by approximately 60%. It is unlikely that overpressures this large would be used in practical CO₂ storage systems. All runs are performed for pure water (no salinity) in isothermal mode at $T = 45$ °C. A length of 1 m of fault zone is simulated and a constant vertical grid spacing of 5 m is used. Capillary pressure parameters were chosen so that maximum $P_{cap}$ is $10^7$ Pa, and $P_{cap}$ vanishes for small gas saturations of $S_g \leq 0.001$. These and other simulation parameters can be seen from the TOUGH2 input file shown in Fig. 24. For this simple 1-D problem, the calculational mesh is generated simply by directly specifying "repeat" elements and connections in the TOUGH2 input file. The 500 m vertical extent of the fault zone is evenly divided into 100 grid blocks of 5 m height. Additional blocks *top 0* and *bot 0* are used to represent boundary conditions. For the 1 m length of the 25 m wide fault zone modeled, interface areas are 25 m². Input data also include COFT and FOFT blocks for generating output data for plotting. For reference we list representative fluid properties used in the simulation in Table 4.
*rldv* ... 1-D vertical column; CO2 migration up a fault zone

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CO2in

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| flt0 | flt1 | 98   | 1     | 1     | 3     | 2.5  | 25.   | -1.  |
| flt99top | 0 | 3    | 2.5   | 1.e-3 | 25.   | -1.  |      |

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| flt0 | flt99top | 0 | 3    | 2.5   | 1.e-3 | 25.   | 1.   |

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GENER----1----*----2----*----3----*----4----*----5----*----6----*----7----*----8

| TIMES----1----*----2----*----3----*----4----*----5----*----6----*----7----*----8 |
|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 8     | 1.E5  | 1.e6  | 1.e7  | 2.e7  | 1.e8  | 1.e9  | 1.e10 | 1.e11 |
| ENDCY----1----*----2----*----3----*----4----*----5----*----6----*----7----*----8 |

Figure 24. TOUGH2 input file for fault zone problem.
Table 4. PVT properties at a temperature of 45 °C at selected pressures, as used in the TOUGH2/ECO2N simulation.

<table>
<thead>
<tr>
<th>Pressure (bar)</th>
<th>120</th>
<th>160</th>
<th>200</th>
<th>240</th>
</tr>
</thead>
<tbody>
<tr>
<td>fluid phase</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>pure water</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>density (kg/m³)</td>
<td>994.768</td>
<td>996.292</td>
<td>997.821</td>
<td>999.354</td>
</tr>
<tr>
<td>viscosity (Pa s)</td>
<td>5.97778e-4</td>
<td>5.98341e-4</td>
<td>5.98929e-4</td>
<td>5.99540e-4</td>
</tr>
<tr>
<td><strong>water with CO₂</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>density (kg/m³)</td>
<td>1005.79</td>
<td>1008.00</td>
<td>1009.94</td>
<td>1011.74</td>
</tr>
<tr>
<td>viscosity (Pa s)</td>
<td>5.97778e-4</td>
<td>5.98341e-4</td>
<td>5.98929e-4</td>
<td>5.99540e-4</td>
</tr>
<tr>
<td>CO₂ mass fraction</td>
<td>5.20592e-2</td>
<td>5.55092e-2</td>
<td>5.76593e-2</td>
<td>5.91875e-2</td>
</tr>
<tr>
<td><strong>gas</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>density (kg/m³)</td>
<td>659.261</td>
<td>760.931</td>
<td>813.504</td>
<td>850.176</td>
</tr>
<tr>
<td>viscosity (Pa s)</td>
<td>5.17641e-5</td>
<td>6.56503e-5</td>
<td>7.45231e-5</td>
<td>8.15904e-5</td>
</tr>
<tr>
<td>water mass fraction</td>
<td>2.14658e-3</td>
<td>2.41648e-3</td>
<td>2.54446e-3</td>
<td>2.62678e-3</td>
</tr>
</tbody>
</table>

5.3.1 Gravity Equilibration

Gravity-equilibrated initial conditions are obtained from a simulation in which the element *bot 0* is removed from the input file. Larger time steps (Δt₁ = 1.e3, Δt₂ = 9.e3 s) are used, along with a tight convergence tolerance of RE₁ = 1.e-10. Pore compressibility is set to 0 in this part of the simulation, so that porosity remains a constant 35 % throughout as fluid pressures change. After 22 time steps and a simulation time of t = 4.72x10⁹ seconds an accurate hydrostatic equilibrium is obtained, with maximum pore velocities of 2x10⁻¹⁹ m/s. Pressure in the lowest grid block, 2.5 m above the lower boundary, is computed as 148.56 bar.

5.3.2 CO₂ Displacement

Migration of CO₂ up the fault zone is simulated with the input file as given in Fig. 24, and using the SAVE file from the gravity equilibration as INCON. The main process in this problem is immiscible displacement of water by CO₂. In response to the applied step change in pressure at the bottom of the fault, CO₂ enters the system at the lower boundary and migrates up the fault, displacing some of the water and also partially dissolving in residual water, while some water also dissolves in the CO₂. The problem is run in two variations, (1) using the Spycher and Pruess (2005) phase partitioning model, and (2) using an evaporation model for water partitioning into the gas phase (parameter IE(12)=1).
Part of the printed output is shown in Fig. 25. Simulation results are plotted in Figs. 26 - 30, with thick solid lines representing variation (1), thick dashed lines representing variation (2), and thin dotted lines showing results from various groups that participated in the code intercomparison study. Variation (1) is considered the most accurate, while variation (2) strongly underestimates the uptake of water by the CO₂ rich phase. Variation (2) was included here to bring out effects of water dissolution in the gas phase that are missed in the simplistic evaporation model, and to offer a comparison to results submitted in the code intercomparison project, all of which employ an evaporation model. The variation (2) results agree closely with the LBNL submission to the code intercomparison project.

The simulated evolution of the system proceeds through four stages (Figs. 26, 27). In Stage 1, CO₂ enters the first grid block above the lower boundary, evolving a gas phase there and causing rapid pressurization that migrates up the fault. Stage 1 ends at approximately $10^4$ seconds when the pressure pulse reaches the top of the fault, causing outflow of water to commence. During the subsequent Stage 2 the CO₂ displacement front migrates up the fault until, after about $3 \times 10^7$ seconds, the front reaches the top. At this time CO₂ discharge from the fault begins, while water discharge is reduced because of relative permeability effects, and also because capillary effects reduce the effective pressure gradient for the aqueous phase at the top of the fault. Stage 3 lasts from approximately $3 \times 10^7$ to $3 \times 10^9$ seconds, and is characterized by two-phase outflow of liquid and gas from the fault. Water continues to be removed from the fault not only by advection, but also by dissolution into the flowing gas phase, causing gas relative permeabilities and flow rates to...
increase. As gas saturations increase capillary pressures get stronger, and at $3.1 \times 10^9$ seconds the effective pressure gradient for the aqueous phase at the top of the fault reverses, leading to downflow of water from the top boundary. The water dissolves into the flowing CO$_2$ stream and is carried right back out at the top. Eventually the entire flow system dries out, and in Stage 4 we have a steady single-phase gas flow up the fault. TOUGH2 recognizes a steady state, and the simulation terminates after 395 time steps and a simulation time of $1.0 \times 10^{11}$ seconds.

Simulation progress and time stepping reflect non-linearities of the flow processes. Many relatively small time steps are required toward the end of Stage 2 as the two-phase front approaches the upper boundary (Fig. 26). Smaller time steps again occur towards the end of Stage 3 when the dryout front approaches the top boundary.

Gas saturations are shown at times of $10^7$ and $10^9$ seconds in Fig. 28. At earlier time there is little difference between the profiles calculated with the two alternative models for water partitioning into gas, while at later time the more accurate Spycher and Pruess (2005) model gives rise to more vigorous dry-out. The pressure profile at $10^7$ seconds has a change in slope at an elevation of 215 m, due to the transition from two-phase conditions below to single-phase conditions above (Fig. 29). The pressure gradient in the two-phase zone is larger than in the single-phase region, indicating that mobility loss from relative permeability effects dominates over mobility gain from the lower viscosity of CO$_2$ as compared to water. At late time pressure gradients are smaller in the single-phase dry-out region, due to increased fluid mobility there, while gradients are larger in the overlying two-phase zone. Upward movement of the dry-out zone results in increasing pressure gradients at the top of the fault, giving rise to a local maximum in water outflow rate at about $3 \times 10^9$ s (Fig. 27). Simulated phase partitioning after $10^7$ seconds is shown in Fig. 30.

Results for the simulated CO$_2$ inventory of the system at $t = 10^7$ and $2 \times 10^7$ seconds are given in Table 5.

<table>
<thead>
<tr>
<th>time</th>
<th>$10^7$ seconds</th>
<th>$2 \times 10^7$ seconds</th>
</tr>
</thead>
<tbody>
<tr>
<td>gas phase</td>
<td>401.498 tonnes</td>
<td>692.639 tonnes</td>
</tr>
<tr>
<td>liquid phase</td>
<td>85.340 tonnes</td>
<td>147.258 tonnes</td>
</tr>
<tr>
<td>total</td>
<td>486.838 tonnes</td>
<td>839.897 tonnes</td>
</tr>
</tbody>
</table>
Figure 26. Simulated CO$_2$ fluxes at bottom (lower frame) and top (upper frame) of fault zone. Thick lines are for variation (1) - rigorous H$_2$O-CO$_2$ phase partitioning, while dashed lines are for variation (2) - evaporation model for H$_2$O partitioning into the CO$_2$-rich phase. Thin lines and symbols represent results submitted in the code intercomparison project. The dashed vertical lines mark the different stages in the evolution of the system.
Figure 27. Simulated water flux at top of fault zone. Thick line is for variation (1), dashed line for variation (2), and thin lines represent results submitted in the code intercomparison project.

Figure 28. Gas saturation profiles at times of $10^7$ and $10^9$ seconds. Thick line is for variation (1), dashed line for variation (2), and thin lines represent results from the code intercomparison project.
Figure 29. Pressure profiles at times of $10^7$ and $10^9$ seconds. Solid lines are for variation (1), dashed lines for variation (2).
Figure 30. Dissolved CO$_2$ mass fraction in aqueous phase (top) and dissolved water mass fraction in gas (bottom) after $10^7$ s. Thick lines are for variation (1), dashed lines for variation (2), and thin lines represent results submitted in the code intercomparison project.
5.4 Problem No. 4 (*rtp7*) - CO₂ Injection into a 2-D Layered Brine Formation

The first industrial-scale CO₂ disposal project to become operational is at the Sleipner Vest field in the Norwegian sector of the North Sea, where approximately 10⁶ tonnes of CO₂ per year have been injected since 1996 through a horizontal well into sands of the Utsira formation. Time-lapse seismic surveys have shown that CO₂ migration at Sleipner is dominated by buoyancy effects and is strongly affected by shale interbeds of low permeability (Lindeberg et al., 2002). The present test problem was patterned after conditions at Sleipner and was designed to investigate CO₂ migration in a heterogeneous sand-shale sequence. It had been included as #7 in the code intercomparison project (Pruess et al., 2002, 2004). A 2-D vertical section was modeled (Fig. C.1, Appendix C), with problem specifications given in Appendix C. The problem was run in several segments to first obtain the initial and boundary conditions, and then inject CO₂ according to specifications. All runs were performed in isothermal mode at a temperature of 37 °C and a salinity of 3.2 wt.-% NaCl.

The grid should be designed in such a way as to obtain “adequate” spatial resolution in regions where significant gradients occur, i.e., near the injection well, and near the shale layers (Fig. C.1). The grid is generated with the MESHMAKER facility of TOUGH2 as a horizontal (x-y) grid and is then rotated by 90 degrees around the x-axis to obtain a vertical section. Subroutine GXYZ was modified to automatically assign “sand” and “shale” domain identifiers to grid blocks at the appropriate elevations (Fig. 31). Gridding in the x-direction starts with 1 m increments at the well, and becomes coarser at increasing distance (Table 6). 28 grid blocks are used to get out to a distance of 6,000 m, followed by a small grid increment of 10⁻³ m to serve as boundary blocks to maintain a hydrostatic pressure profile. Gridding in the y-direction also uses a 1 m increment at the well, with coarser gridding below and above. The shale layers are represented as single grid layers of 3 m height, with 3 m gridding also in the sands above and below. The thickness of the grid is 1 m. Overall the gridding is considered rather coarse, meeting minimum requirements for spatial resolution at the well and at the shale layers.

```fortran
DO1 J=1,NY
    JM=MOD(J-1,35)+1
    NOVJ=(J-1)/35
    IF(J.GT.1) YJ=YJ+DY(J)/2.+DY(J-1)/2.
C
C.....10-12-01: add domain identifiers
    dom='sand'
    yj52=yj-52.
    IF(yj52.ge.0..and.mod(yj52,33.).le.3.) dom='shale'

Figure 31. Code fragment of subroutine GXYZ (module meshm.f), showing modifications for assigning domain identifiers to the heterogeneous sand-shale medium.
```
Table 6. MESHMAKER input data for grid generation.

<table>
<thead>
<tr>
<th>X</th>
<th>Y</th>
<th>Z</th>
</tr>
</thead>
<tbody>
<tr>
<td>90.</td>
<td>1.</td>
<td>2.</td>
</tr>
<tr>
<td>30.</td>
<td>40.</td>
<td>50.</td>
</tr>
<tr>
<td>300.</td>
<td>500.</td>
<td>500.</td>
</tr>
<tr>
<td>500.</td>
<td>1.e-3</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>N</th>
<th>X</th>
<th>Y</th>
<th>Z</th>
</tr>
</thead>
<tbody>
<tr>
<td>29</td>
<td>1.</td>
<td>1.</td>
<td>4.</td>
</tr>
<tr>
<td>40.</td>
<td>50.</td>
<td>100.</td>
<td></td>
</tr>
<tr>
<td>500.</td>
<td>500.</td>
<td>500.</td>
<td></td>
</tr>
<tr>
<td>500.</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

---

5.4.1 Gravity Equilibration

Initial conditions are generated in stages. A first simulation run uses a slightly modified version of the input file shown in Fig. 32 and involves just the column of boundary grid blocks beyond \( x = 6,000 \) m. Thermodynamic properties are specified as \( P = 110 \) bars, \( T = 37 \) °C, salinity \( X_s = 0.032 \), \( \text{CO}_2 \) mass fraction \( X_{\text{CO}_2} = 4.54104 \times 10^{-4} \). The latter value was obtained by trial and error, executing a few single-grid block initializations to obtain the desired \( P_{\text{CO}_2} = 0.5 \) bar. Pressure is held constant at \( P = 110 \) bar at the elevation of the injection node (22 m) and the system is run to gravity equilibrium. To facilitate reaching an accurate equilibrium state, the shale layers are given the same absolute permeability as the sand layers for this simulation. Gravity equilibrium using a tight convergence tolerance of \( 10^{-8} \) is attained in seven time steps, corresponding to a simulation time of \( 3.25 \times 10^9 \) s. Maximum pore velocities in the equilibrium state are below \( 10^{-17} \) m/s. A second run with the full two-dimensional grid is then performed, using the same initialization as for the 1-D gravity equilibration just described, and maintaining the 1-D gravity equilibrium as boundary conditions at the right hand side. For this calculation we again specify the same absolute permeability for shale as for sand. Gravity equilibration in the 2-D grid takes 12 time steps and a simulation time of \( 2.93 \times 10^9 \) s.

5.4.2 Response to CO\(_2\) Injection

CO\(_2\) injection at a constant prescribed rate of 0.1585 kg/s is simulated with the input file as shown in Fig. 32. This input file specifies a total simulation time of \( 63.1152 \times 10^6 \) s (2 years), with additional printout generated at times of 30 days (\( 2.592 \times 10^6 \) s) and one year (\( 31.5576 \times 10^6 \) s). A portion of the printed output is shown in Fig. 33, and results are given in Figs. 34-42.
*rtp7* ... test problem # 7: CO2 in layered formation
ROCKS----1----*----2----*----3----*----4----*----5----*----6----*----7----*----8
sand  2 2600.e00 .35 3.e-12 3.e-12 3.e-12 2.51 920.
    0.0e-10
    7 0.40 0.20 1. 0.05
    7 0.40 0.20 2.79e-4 1.e7  .999
    0.0e-10
    7 0.40 0.20 1. 0.05
    7 0.40 0.20 1.61e-4 1.e7  .999
MULTI----1----*----2----*----3----*----4----*----5----*----6----*----7----*----8
3 3 3 6
SELEC....2....3....4....5....6....7....8....9....10....11....12....13....14....15....16
1 0 0 0 0 0 0 0
    .8 .8
START----1----*----2----*----3----*----4----*----5----*----6----*----7----*----8
---*-----1 MOP: 123456789*123456789*1234 ---*----5----*----6----*----7----*----8
PARAM----1----*----2----*----3----*----4----*----5----*----6----*----7----*----8
1 600 99991000 00000000 4 3
63.1152e6 -1. -9.81
1.e2  1.E-5 1.E00
110.e5  3.2e-2 .454104e-03 37.
SOLVR----1----*----2----*----3----*----4----*----5----*----6----*----7----*----8
5  Z1  O0  8.0e-1  1.0e-7
GENER----1----*----2----*----3----*----4----*----5----*----6----*----7----*----8
A15 1inj 1                   1     COM3      .1585
TIMES----1----*----2----*----3----*----4----*----5----*----6----*----7----*----8
3 2.592e6 31.5576e6 63.1152e6
FOFT ----1----*----2----*----3----*----4----*----5----*----6----*----7----*----8
A14 1  sand .2500E+01 .5000E+01 .5000E+00 .2025E+02-.5000E+00
A15 1  sand .1000E+01 .2000E+01 .5000E+00 .2200E+02-.5000E+00
A16 1  sand .2500E+01 .5000E+01 .5000E+00 .2375E+02-.5000E+00
A1G 1  sand .3000E+01 .6000E+01 .5000E+00 .8350E+02-.5000E+00
A15 2  sand .1000E+01 .2000E+01 .5000E+00 .2200E+02-.5000E+00
COFT ----1----*----2----*----3----*----4----*----5----*----6----*----7----*----8
A14 1A15 1  2 .1250E+01 .5000E+00 .1000E+01 .1000E+01
A15 1A15 2  1 .5000E+00 .5000E+00 .1000E+01
A15 1A16 1  2 .5000E+00 .1250E+01 .1000E+01 .1000E+01
GOFT ----1----*----2----*----3----*----4----*----5----*----6----*----7----*----8
ENDCY----1----*----2----*----3----*----4----*----5----*----6----*----7----*----8

Figure 32. TOUGH2 input file for CO2 injection into a 2-D layered brine formation.
Figure 33. Part of printed output for problem of CO2 injection into a layered brine formation.

Startup of CO2 injection causes pressures to rise initially, most strongly and rapidly in the well block, and less strongly and with some time delay at more distant locations (Fig. 34). The system quickly establishes quasi-steady flow conditions at the well block (Fig. 35), and the sum of the absolute values of the flow rates quickly approaches the total injection rate of 0.1585 kg/s. As gas saturations increase near the injection point, injection pressures actually decline slowly. The plot of time steps vs. time shows decreasing slope over time (Fig. 34), reflecting an overall trend towards increasing time step sizes as the simulation progresses.

Gas saturations at and near the well block (A15 1) show interesting non-monotonic behavior (Fig. 36), due to an interplay of gas-liquid counterflow, relative permeability effects and precipitation of solid salt. After approximately 4.5x10^6 s, gas saturation at the well block reaches a maximum value of 75.1 % and then declines slowly. This decline is caused by increasing salt precipitation (Fig. 37). Liquid saturation declines rapidly initially, but later almost stabilizes near 20 % (note the logarithmic time scale on Fig. 37), due to capillary-driven inflow of liquid from
neighboring grid blocks. At early time liquid flow is away from the well block, but at approximately $5 \times 10^5$ s liquid flow reverses and subsequently is towards the well block, as capillary pressures there become stronger due to increasing gas saturation (Fig. 38). As time goes on, gas saturations in the blocks adjacent to the well block continue a slow increase (Fig. 36). This reduces relative permeability to liquid, but liquid flow rates into the well block remain essentially constant for a while, because increasing strength of capillary pressure in the well block compensates for the reduction in relative permeability. After approximately $10^7$ s, capillary pressure in the well block reaches the cutoff value of $10^7$ Pa specified in the input file (Fig. 32). Subsequently the flow of aqueous phase towards the well block brings in less water than is carried out by the gas phase, leading to accelerated precipitation and rapid dry-out. This explains the very rapid increase in gas saturation in the well block at approximately $1.1 \times 10^7$ s. Fig. 36 shows similar patterns of gas saturation behavior in grid blocks neighboring the well block that dry out at later times. The evolution of solid saturations in selected blocks is shown in Fig. 39.

The simulation of this problem previously submitted by LBNL for the code intercomparison project did not generate any solid precipitate (Pruess et al., 2002, 2004). The different behavior seen in the present simulation is due to the much more vigorous removal of water into the flowing gas stream, as compared to the evaporation model for water partitioning into the gas phase that had been used in the earlier calculation. The mechanisms contributing to solid precipitation and formation dry-out near the injection well are believed to be represented realistically in the present simulation, but the space discretization near the injection well is rather coarse, and considerably finer gridding would be needed to achieve accurate results.

Figs. 40-42 show contour maps of pressure, gas saturation, and dissolved CO$_2$ mass fraction after two years of simulation time. These results are all very similar to our earlier calculations using an evaporation model for water in the CO$_2$ rich phase. Highest gas saturations of approximately 60 % occur beneath the shale layers at elevations of 52, 85, and 118 m. Gas is just beginning to reach the top shale layer at an elevation of 151 m. CO$_2$ mass fraction dissolved in the aqueous phase after two years is in the range of 4.5 - 4.85 % throughout most of the two-phase zone, with smaller but significant CO$_2$ concentrations occurring beyond the two-phase region.
Figure 34. Time evolution of pressures in two grid blocks (A15 1 and A1G 1) and time stepping for CO$_2$ injection into a layered brine formation.

Figure 35. Gas flow rates at the well block. Gas flow is away from the well block, and is plotted as a positive or negative, depending upon whether the well block is the first or second element in a flow connection.
Figure 36. Gas saturations at the well block and its neighbors (above - A16 1; outward - A15 2; below - A14 1). Gas saturations at block A1G 1 at an elevation of 83.5 m (61.5 m above well block) are also shown.

Figure 37. Phase saturations at the well block (A15 1).
Figure 38. Absolute values of aqueous phase flow rates between the well block and neighboring grid blocks. Up to approximately $10^5$ s flow is away from the well block, then reverses.

Figure 39. Solid saturations (fraction of void space taken up by solid precipitate) in the well block and its neighbors.
Figure 40. Contour map of fluid pressures after 2 years of CO₂ injection.

Figure 41. Contour map of gas saturations after 2 years of CO₂ injection.
Figure 42. Contour map of dissolved CO₂ mass fractions after 2 years of CO₂ injection.

Table 7. CO₂ inventory (in units of 10⁶ kg) for injection into a saline 2-D layered system.

<table>
<thead>
<tr>
<th></th>
<th>t = 0</th>
<th>30 days</th>
<th>1 year</th>
<th>2 years</th>
</tr>
</thead>
<tbody>
<tr>
<td>total CO₂</td>
<td>0.1787</td>
<td>0.5893</td>
<td>5.178</td>
<td>10.18</td>
</tr>
<tr>
<td>CO₂ injected</td>
<td>0.0000</td>
<td>0.4108</td>
<td>5.002</td>
<td>10.00</td>
</tr>
<tr>
<td>CO₂ (aq.)</td>
<td>0.1787</td>
<td>0.2708</td>
<td>1.120</td>
<td>2.037</td>
</tr>
<tr>
<td>CO₂ (gas)</td>
<td>0.0000</td>
<td>0.3185</td>
<td>4.058</td>
<td>8.140</td>
</tr>
<tr>
<td>fraction of CO₂ in aq. phase</td>
<td>1.000</td>
<td>0.4596</td>
<td>0.2163</td>
<td>0.2002</td>
</tr>
</tbody>
</table>
6. Concluding Remarks

ECO2N is a new fluid property module for the multiphase, multicomponent simulator TOUGH2, Version 2.0. It provides capabilities for modeling advective and diffusive flow and transport in multidimensional heterogeneous systems containing H₂O - NaCl - CO₂ mixtures. Process capabilities include coupling between fluid and heat flow, partitioning of H₂O and CO₂ among different phases, and precipitation/dissolution of solid salt. The code represents thermophysical properties of brine-CO₂ mixtures generally within experimental accuracy for the range of conditions of interest in geologic disposal of CO₂. A fluid property table provided with ECO2N covers temperatures from ambient to 103 °C and pressures from ambient to 600 bar. Software to generate property tables is provided with ECO2N, making possible applications to a more extensive range of conditions. Super- as well as sub-critical conditions may be modeled, but the code currently has no provisions to treat separate liquid and gas CO₂ phases, or transitions between them.

Acknowledgement

Thanks are due to Sally Benson and Jens Birkholzer for a careful review of the manuscript and the suggestion of improvements. This work was supported by the Director, Office of Science, Office of Basic Energy Sciences of the U.S. Department of Energy, and by the Zero Emission Research and Technology project (ZERT) under Contract No. DE-AC03-76SF00098.
References


Lindeberg, E., P. Bergmo and A. Moen. The Long-Term Fate of CO2 Injected into an Aquifer, paper G1-4, presented at Sixth International Conference on Greenhouse Gas Technologies (GHGT-6), Kyoto, Japan, October 1-4, 2002.


APPENDIX A

Code Intercomparison Problem 3: Radial Flow from a CO2 Injection Well

1. INTRODUCTION AND GENERAL DESCRIPTION
This problem addresses two-phase flow of CO2 and water for simplified flow geometry and medium properties. The aquifer into which injection is made is assumed infinite-acting, homogeneous, and isotropic. Gravity and inertial effects are neglected, injection is made at a constant mass rate, and flow is assumed 1-D radial (line source). Under the conditions stated the problem has a similarity solution where dependence on radial distance R and time t occurs only through the similarity variable $\xi = R^2/t$ (O’Sullivan 1981; Doughty and Pruess 1992).

2. LIST OF PROCESSES BEING STUDIED
Two-phase flow of CO2 and water subject to relative permeability and capillary effects. Change of fluid density, viscosity, and CO2 solubility with pressure and salinity. Formation dry-out with precipitation of salt.

3. DEFINITION OF THE PROBLEM AND INPUT DATA
Problem parameters are summarized in Tables A.1 and A.2.

4. PROBLEM VARIATIONS
Neglect salinity of the aqueous phase. Include non-isothermal effects. Include permeability changes due to precipitation. Inject gas that is 50 % CO2, 50 % N2.

5. DEFINITION OF RESULTS TO BE CALCULATED
Data on CO2 and brine density and viscosity, and CO2 solubility, for the range of thermodynamic conditions encountered in the problem. Gas saturation, dissolved CO2 mass fraction, fraction of void space containing precipitated salt, and fluid pressure as functions of the similarity variable $\xi = R^2/t$. (Use both profiles at constant time and time-series data at a specific location for plotting.)

6. COMPARISON CRITERIA
Results should match within +/- 5 %.

7. REFERENCES

& proposed by Karsten Pruess; e-mail: K_Pruess@lbl.gov


**Table A.1 Hydrogeologic parameters.**

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Permeability</td>
<td>$k = 10^{-13}$ m$^2$</td>
</tr>
<tr>
<td>Porosity</td>
<td>$\phi = 0.12$</td>
</tr>
<tr>
<td>Pore compressibility</td>
<td>$c = 4.5 \times 10^{-10}$ Pa$^{-1}$</td>
</tr>
<tr>
<td>Aquifer thickness</td>
<td>100 m</td>
</tr>
<tr>
<td>Relative permeability</td>
<td></td>
</tr>
<tr>
<td>liquid: van Genuchten function</td>
<td></td>
</tr>
<tr>
<td>$k_{rl} = \sqrt{S^* \left(1 - \left(1 - S^* \frac{1}{\lambda}\right)^{\frac{1}{\lambda}}\right)}$</td>
<td>$S^* = \frac{(S_l - S_{lr})}{(1 - S_{lr})}$</td>
</tr>
<tr>
<td></td>
<td>$S_{lr} = 0.30$</td>
</tr>
<tr>
<td></td>
<td>$\lambda = 0.457$</td>
</tr>
<tr>
<td>gas: Corey curve (1954)</td>
<td></td>
</tr>
<tr>
<td>$k_{rg} = (1 - \hat{S})^2 (1 - \hat{S}^2)$</td>
<td>$\hat{S} = \frac{(S_l - S_{lr})}{(1 - S_{lr} - S_{gr})}$</td>
</tr>
<tr>
<td></td>
<td>$S_{gr} = 0.05$</td>
</tr>
<tr>
<td>Capillary pressure</td>
<td></td>
</tr>
<tr>
<td>van Genuchten function (1980)</td>
<td></td>
</tr>
<tr>
<td>$P_{cap} = -P_0 \left(S^* \frac{1}{\lambda - 1}\right)^{1-\lambda}$</td>
<td>$S^* = \frac{(S_l - S_{lr})}{(1 - S_{lr})}$</td>
</tr>
<tr>
<td></td>
<td>$S_{lr} = 0.0$</td>
</tr>
<tr>
<td></td>
<td>$\lambda = 0.457$</td>
</tr>
<tr>
<td></td>
<td>$P_0 = 19.61$ kPa</td>
</tr>
</tbody>
</table>

**Table A.2 Initial conditions and injection specifications**

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Pressure</td>
<td>120 bar</td>
</tr>
<tr>
<td>Temperature</td>
<td>45 °C</td>
</tr>
<tr>
<td>Salinity</td>
<td>15 wt.-% NaCl</td>
</tr>
<tr>
<td>CO2 injection rate</td>
<td>100 kg/s</td>
</tr>
</tbody>
</table>
1. INTRODUCTION AND GENERAL DESCRIPTION
This problem explores CO2 loss from storage through a leaky fault, using a highly simplified 1-D linear flow geometry. It is envisioned that an aquifer into which CO2 disposal is made is intersected by a vertical fault, which establishes a connection through an otherwise impermeable caprock to another aquifer 500 m above the storage aquifer (Fig. B.1a). This situation is idealized by assuming 1-D flow geometry and constant pressure boundary conditions as shown in Fig. B.1b (Pruess and García, 2000).

![Figure B.1 Schematic of the fault zone model (a) and applied boundary conditions (b).](image)

2. LIST OF PROCESSES BEING STUDIED
Immiscible displacement of water by CO2 subject to pressure, gravity, and capillary pressure effects.
Change of fluid density, viscosity, and CO2 solubility with pressure.
Formation dry-out.

3. DEFINITION OF THE PROBLEM AND INPUT DATA
Hydrogeologic parameters are identical to those of problem 3 (Table A.1), except that porosity is increased to 35 %. The fault zone is assumed to be 25 m wide and 500 m tall, with boundary conditions as given in Fig. B.1b. The reservoir fluid is assumed to be pure water (no salinity). Initial conditions are pressures in hydrostatic equilibrium relative to $P = 100$ bar at the top; temperature is held constant at $T = 45 ^\circ C$ throughout.

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* proposed by Karsten Pruess; e-mail: K_Pruess@lbl.gov
4. PROBLEM VARIATIONS
Include salinity of the aqueous phase and permeability changes due to precipitation. Include non-isothermal effects. Assume gas composition is 50 % CO2, 50 % N2.

5. DEFINITION OF RESULTS TO BE CALCULATED
Data on CO2 and water density and viscosity, and CO2 solubility, for the range of thermodynamic conditions encountered in the problem. Vertical profiles of gas saturation, fluid pressure, and dissolved CO2 mass fraction at different times. CO2 inventory in gas and liquid phases after 10^7 seconds. Mass flow rates of CO2 at the bottom and of water at the top vs. time (normalized for a 1 m thick section).

6. COMPARISON CRITERIA
Results should match to with +/- 5 %.

7. REFERENCES
APPENDIX C
Code Intercomparison Problem 7: CO₂ Injection into a 2-D Layered Brine Formation#

1. INTRODUCTION AND GENERAL DESCRIPTION
This test problem is patterned after the CO₂ injection project at the Sleipner Vest field in the Norwegian sector of the North Sea, and is intended to investigate the dominant physical processes associated with the injection of supercritical CO₂ into a layered medium. Significant simplifications have been made, the most important of which is the assumption of isothermal conditions (37 °C, the ambient temperature of the formation). CO₂ injection rates (1,000,000 tonnes per year), system geometry, and system permeabilities correspond approximately to those at Sleipner, although no attempt was made to represent details of the permeability structure within the host formation. Injection of the supercritical CO₂, which is less dense than the saline formation waters into which it is injected, causes it to rise through the formation. Its rate of ascent, however, is limited by the presence of four relatively low permeability shales. The top and bottom of the formation is assumed to be impermeable. The only reactive chemistry considered in this problem is the dissolution of CO₂ in the aqueous phase.

2. LIST OF PROCESSES BEING STUDIED
   a) Gravity-driven advection in response to strong vertical and lateral density gradients induced by the injection of CO₂ into saline formation water.
   b) Density, viscosity, and solubility formulations of water and CO₂ as a function of pressure and temperature (P and T).

3. DEFINITION OF THE PROBLEM AND INPUT DATA
   System Geometry:
The system is idealized as a two dimensional symmetric domain perpendicular to the horizontal injection well which has a screen length of 100 meters (Figure C.1). A one meter thick section perpendicular to the horizontal well is considered. The thickness of the formation at the injection site is 184 meters. The injection point is 940 meters below the sea floor, while the ocean depth at the site is 80 meters. The formation is assumed to consist of four lower permeability shale units 3 meters thick which are distributed within the high permeability sand. Each shale unit is separated by 30 meters. The well is 30 meters below the lowest shale unit, while the bottom of the aquifer is another 22 meters below the well.

# proposed by Carl Steefel; e-mail: CISteefel@lbl.gov
Figure C.1  Schematic representation of geometry for CO2 injection in Utsira Formation.

Boundary conditions:
No heat or mass flux is allowed across any of the boundaries except the vertical boundary 6,000 meters from the injection well. This boundary is fixed at hydrostatic pressure, thus allowing flow into and out of the domain so as to avoid overpressuring the formation. The 6,000 meter boundary is chosen, however, to be far enough from the injection well that the CO2 does not reach this boundary after 2 years of injection.

Initial conditions (Table C.1):

a) $T = 37$ °C (isothermal throughout)
b) $P =$ hydrostatic (approximately 110 bars at injection point, approximately 90 bars at top of formation).
c) CO2 in the aqueous phase in equilibrium with a $P_{CO2}$ of 0.5 bars, a typical value for sedimentary formation waters at the temperature we are considering.

Table C.1  Initial conditions and injection specifications

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>Pressure at well</td>
<td>110 bar</td>
</tr>
<tr>
<td>Temperature</td>
<td>37 °C</td>
</tr>
<tr>
<td>Salinity</td>
<td>3.2 wt.-% NaCl</td>
</tr>
<tr>
<td>CO2 injection rate</td>
<td>0.1585 kg/s in half space</td>
</tr>
</tbody>
</table>
Injection specifications (Table C.1):

a) Temperature = 37 °C

b) Injection rate: 31.7 kg/s over entire screen length (100 meters), corresponding to 0.317 kg/s for the 1 meter thick section considered. Because of symmetry, injection rate in half space is therefore 0.1585 kg/s.

c) Height of well cell: 1 meter.

d) Injection time scale: 2 years

Input data (Table C.2):

a) Capillary pressure and liquid relative permeability described with van Genuchten (1980) functions; gas relative permeability after Corey (1954). Porosity is 35% for sands, 10.25% for shales.

b) Fully saturated permeability (k = 3 x 10^{-12} m^2 in sand layers, 10^{-14} m^2 in shales)

c) Density, viscosity, and solubility in water of CO₂ as functions of P and T (Span and Wagner, 1996).

d) Vapor-liquid equilibrium properties of water.

4. PROBLEM VARIATIONS
Include non-isothermal effects by making the CO₂ injection temperature equal to 65 °C.

5. RESULTS TO BE CALCULATED
Liquid and gas saturations as a function of space and time. CO₂ concentration in the aqueous phase as a function of space. Gas and liquid fluxes.

6. COMPARISON CRITERIA
Results should match within +/- 5%.

IMPORTANT NOTICE
A first version of this test problem had specified that gas relative permeability was to be calculated from a van Genuchten function. In a workshop held in October 2001 in Berkeley, participants in the code intercomparison project agreed to change this specification to using a Corey (1954) curve instead, with parameters as given in Table C.2. In two subsequently issued laboratory reports with results of the code intercomparison project (Pruess and García, 2002; Pruess et al., 2002), the original van Genuchten specifications were inadvertently retained, even though all simulations had used the altered (Corey, 1954) specifications.
Table C.2  Hydrogeologic parameters

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Sands: $3 \times 10^{12} \text{ m}^2$; Shales: $10^{-14} \text{ m}^2$</th>
</tr>
</thead>
<tbody>
<tr>
<td>Permeability</td>
<td></td>
</tr>
<tr>
<td>Porosity</td>
<td></td>
</tr>
<tr>
<td>Aquifer thickness</td>
<td>$184 \text{ m}$</td>
</tr>
<tr>
<td>Relative permeability</td>
<td></td>
</tr>
<tr>
<td>liquid: van Genuchten function (1980)</td>
<td></td>
</tr>
<tr>
<td>$k_{rl}$</td>
<td>$\sqrt{S^<em>} \left{ 1 - \left[ 1 - \left( S^</em> \right)^{1/\lambda} \right] \right} \lambda^2$</td>
</tr>
<tr>
<td>irreducible water saturation</td>
<td>$S^* = \frac{(S_l - S_{lr})}{(1 - S_{lr})}$</td>
</tr>
<tr>
<td>exponent</td>
<td>$S_{lr} = 0.20$</td>
</tr>
<tr>
<td></td>
<td>$\lambda = 0.400$</td>
</tr>
<tr>
<td>gas: Corey (1954)</td>
<td></td>
</tr>
<tr>
<td>$k_{rg}$</td>
<td>$\left( 1 - \hat{S} \right)^2 \left( 1 - \hat{S}^2 \right)$</td>
</tr>
<tr>
<td>irreducible water saturation</td>
<td>$\hat{S} = \frac{(S_l - S_{lr})}{(1 - S_{lr} - S_{gr})}$</td>
</tr>
<tr>
<td>irreducible gas saturation</td>
<td>$S_{lr} = 0.20$</td>
</tr>
<tr>
<td></td>
<td>$S_{gr} = 0.05$</td>
</tr>
<tr>
<td>Capillary pressure</td>
<td></td>
</tr>
<tr>
<td>van Genuchten function (1980)</td>
<td></td>
</tr>
<tr>
<td>$P_{cap}$</td>
<td>$- P_0 \left( \left( S^* \right)^{-1/\lambda} - 1 \right)^{1-\lambda}$</td>
</tr>
<tr>
<td>irreducible water saturation</td>
<td>$S^* = \frac{(S_l - S_{lr})}{(1 - S_{lr})}$</td>
</tr>
<tr>
<td>exponent</td>
<td>$S_{lr} = 0.20$</td>
</tr>
<tr>
<td></td>
<td>$\lambda = 0.400$</td>
</tr>
<tr>
<td>strength coefficient</td>
<td>Sand: $P_0 = 3.58 \text{ kPa}$; Shale: $P_0 = 62.0 \text{ kPa}$</td>
</tr>
</tbody>
</table>

7. REFERENCES


